Motor Controllers
AC Semiconductor Motor Controller
Type RSHL MIDI SMART

- Soft starting and stopping of 3-phase induction squirrel cage motors
- 2-phase control with integral bypassing of semiconductors
- Low inrush and reduced vibration during starting
- Rated operational voltage: up to 600 VAC, 50/60Hz
- Rated operational current: up to 18A AC-53b
- LED status indicators
- Integrated device over-temperature protection*
- Integrated motor over-temperature protection
- Integrated auxiliary relays for end of ramp and alarms
- DIN rail mounting
- Current limit setting for 150%, 250%, 350%, 450% of full load current.
- Integrated overload protection with options for class 10 or class 20
- Monitoring of phase sequence, phase loss and phase-imbalance

Product Description

The RSHL Midi Smart is a compact easy-to-use AC semiconductor motor controller with which 3-phase motors with nominal currents up to 18A can be soft started and/or soft stopped. The RSHL Midi Smart controls 2 phases only, while the third phase is continously connected to the load. Soft starting and soft stopping is achieved by controlling the motor voltage. During normal running operation (<20A) the semiconductors are bypassed by internal electromechanical relays. Ramp profile, overload trip class, current limit settings and alarm parameters are user adjustable via the front panel.
Eight LEDs on the front panel indicate the states and alarms of the softstarter. The RSHL MIDI Smart includes an End of ramp auxiliary relay, Alarm auxiliary relay, and overtemperature protection. The RSHL Midi Smart has an integrated Current Limit and Overload Protection. The RSHL Midi Smart comes with an integrated heatsink and is ready to mount on DIN rail.

Ordering Key

RSH L 48 18 C V21

- **H-line Motor Controller**
- **Current limit & overload protection**
- **Rated operational voltage**
- **Rated operational current**
- **Control voltage**
- **Options**

Type Selection

Type	Rated Operational Voltage Ue	Rated Operational Current Ie	Control Voltage Uc	Options
RSHL: H-line motor controller with current limit and motor overload protection	22: 127/220VACrms, 50/60Hz 48: 230/400VACrms, 50/60Hz 277/480VACrms, 50/60Hz 60: 346/600VACrms, 50/60Hz	02: 0.6 - 2 A AC-53b 05: 2 - 5 A AC-53b 12: 4.5 - 12 A AC-53b 18: 5 - 18 A AC-53b	C: 24 - 550 VAC/DC	V21: End of Ramp Relay, Motor Over-Temperature Protection and Alarm Auxiliary Relay. Internal over-temperature protection*

* Internal over-temperature protection is only for RSHL...18CV21

Selection Guide

Rated operational voltage U_e	Rated operational current I_e 2A AC-53b	5A AC-53b	12A AC-53b	18A AC-53b
220VACrms	**RSHL2202CV21**	**RSHL2205CV21**	**RSHL2212CV21**	**RSHL2218CV21**
400/ 480VACrms	**RSHL4802CV21**	**RSHL4805CV21**	**RSHL4812CV21**	**RSHL4818CV21**
600VACrms	**RSHL6002CV21**	**RSHL6005CV21**	**RSHL6012CV21**	**RSHL6018CV21**

Conductor Data

Line conductors: **L1, L2, L3, T1, T2, T3**	
according to EN 60947-1	
flexible	2.5 ..... 10mm²
	2.5 ..... 2 x 4mm²
rigid (solid or stranded)	2.5 ..... 10mm²
flexible with ferrule	2.5 ..... 10mm²
UL/CSA rated data	
flexible	AWG14…8
	AWG14…2 x 10
rigid (solid or stranded)	AWG14…8
Terminal screws	6xM4 (cage clamp)
Tightening torque	2.0Nm (22lb.in) with Posidrive bit 2
Stripping length	8.0mm

Secondary conductors: **A1, A2, A3, A4, P1, P2, 34, 31/41, 42**	
according to EN 60998	
flexible	0.5 ..... 1.5mm²
flexible with ferrule	0.5 ..... 1.5mm²
rigid (solid)	0.5 ..... 2.5mm²
UL/CSA rated data	AWG22…12
Terminal screws	9xM3 (cage clamp)
Tightening torque	0.5Nm (4.5lb.in) with Philips bit 0
Stripping length	6.0mm

General Specifications

Form designation	1
Weight	620g (approx.)
Mounting	DIN Rail 35mm
Housing material	Polyamide (conforms to UL 94 V0)

Status Relays

Auxiliary relay	
End of ramp	Normally Closed (21 : 22)
	Normally Open (21 : 24)
Alarm relay output	Normally Closed (95 : 96)
Auxiliary relay contact capacity	2A, 250VAC
	2A, 30VDC

Supply Specification

Rated operational voltage		
Ue through L1, L2 L3	RSHL22..	127/220VAC -15% / +10%
	RSHL48..	230/400VAC -15% / +10%
		277/480VAC -15% / +10%
	RSHL60..	346/600VAC -15% / +10%
Blocking voltage	RSHL 22...	800 V_p
	RSHL 48...	1200 V_p
	RSHL 60...	1600 V_p
Rated AC frequency		50/60Hz ±10%
Rated insulation voltage		630V, accord. to EN 60947-1
Dielectric strength		
Dielectric withstand voltage		
Supply to input		2.5 kVrms
Supply to heatsink		2.5 kVrms
Supply to external supply		2.5 kVrms
Integrated varistor		yes

Input Specifications

Rated control input voltage Uc A1: A2	24 - 550 VAC/DC
Rated AC frequency	50/60Hz ±10%
Max. control input current	3mA
Response time input to output	400 ms
Dielectric strength	
Dielectric withstand voltage	
Input to supply	2.5 kVrms
Input to heatsink	2.5 kVrms

External Supply Specifications

External supply voltage Us, A3:A4	24VAC/DC -15% / +10%
Rated AC frequency	50/60Hz ±10%
Rated supply current	250mAAC/DC
Dielectric strength	
Dielectric withstand voltage	
Supply to input	2.5 kVrms
Supply to heatsink	2.5 kVrms

Load Ratings

		RSHL22..CV21 / RSHL48..CV21	RSHL60..CV21
IEC rated operational current Ie (AC-53b)	RSHL..02CV21	2A	2A
	RSHL..05CV21	5A	5A
	RSHL..12CV21	12A	12A
	RSHL..18CV21	18A	18A
Overload cycle according to EN/IEC 60947-4-2[1]			
@ 40˚C surrounding temp.	RSHL..02CV21	2: AC-53b : 4-5 : 0	2: AC-53b : 4-5 : 0
	RSHL..05CV21	5: AC-53b : 4-5 : 2.4	5: AC-53b : 4-5 : 2.4
	RSHL..12CV21	12: AC-53b : 4-5 : 21	12: AC-53b : 4-5 : 26
	RSHL..18CV21	18: AC-53b : 4-5 : 62	18: AC-53b: 4-5 : 62
Number of starts per hour @40˚C[2]	RSHL..02CV21	360	360
	RSHL..05CV21	290	290
	RSHL..12CV21	116	100
	RSHL..18CV21	50	50
Minimum full load current	RSHL..02CV21	0.6 AAC rms	0.6 AAC rms
	RSHL..05CV21	1.5 AAC rms	1.5 AAC rms
	RSHL..12CV21	4.5 AAC rms	4.5 AAC rms
	RSHL..18CV21	5 AAC rms	5 AAC rms

[1] Applicable with the overload profile specified in Overload Cycle and Starting Duty section
[2] Taken from tables referring to 45mm spacing.

Motor Ratings

IEC rated operational current Ie (AC-53b)		2A	5A	12A	18A
Assigned motor rating @60˚C/UL rating @60˚C	220VACrms	0.5kW/ 0.5HP	1.1kW/ 1.5HP	3kW/ 3HP	4kW/ 5HP
	400 VACrms	0.75kW/ 0.75HP	2.2kW/ 3HP	5.5kW/ 7.5HP	7.5kW/ 10HP
	480VACrms	1.1kW/ 1HP	2.2kW/ 3HP	5.5kW/ 7.5HP	7.5kW/ 10HP
	600VACrms	1.1kW/ 1HP	3kW/ 5HP	7.5kW/ 10HP	11kW/ 15HP

Environmental Specifications

Operating temperature	-20°C to +60°C (-4°F to +140°F)
Storage temperature	-50°C to +85°C (-58°F to +185°F)
Relative humidity	<95% non-condensing @40°C
Pollution Degree	2

Degree of Protection	IP20 (EN/IEC 60529)
Installation category	III
Installation Altitude	Above 1000m derate linearly by 1% of unit FLC per 100m to a maximum altitude of 2000m

Current Limit Feature

% of full Load Current	Suitable for type of load	Time inrush current is limited (t_{inrush})	Function after (t_{inrush}) and RSHL is not fully ON
150%	Light	5s	Device continue with the Standard Profile settings (Parameter 1)
250%	Light	5s	
350%	Slightly heavy	10s	
450%	Heavy	20s	

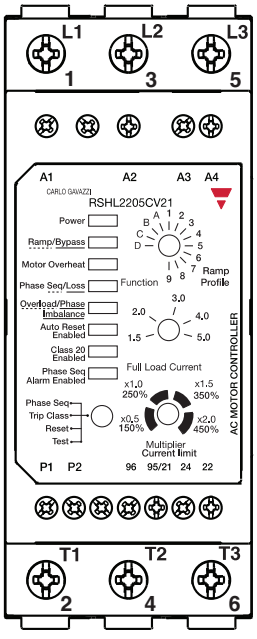
Note: In Current Limit Operation, no soft stop is offered. The motor is left coasting when control is removed.

Standards

Approvals	UL (E172877), cUL
CE Marking LVD	IEC/ EN 60947-4-2
EMCD : Immunity	IEC/ EN 61000-6-4
Emission	IEC/ EN 61000-6-2
Electrostatic Discharge ESD Immunity	IEC/ EN 61000-4-2 8kV, PC2 Air discharge 4kV, PC2 Contact
Electrical fast transient/ Burst Immunity	IEC/ EN 61000-4-4
Output	2kV, PC2
Input	2kV, PC2
Electrical Surge Immunity	IEC/ EN 61000-4-5, PC2
Outpt, line to line	1kV
Output, line to earth	2kV
Input, line to line	1kV
Input, line to earth	1kV
Radiated Radio Frequency (Does not meet EN61000-6-2-2005 requirements requesting tests up to 2.7GHz)	EN 61000-4-3, PC1 10V/m, 80-1000MHz
Conducted radio-frequency immunity	IEC/ EN 61000-4-6, PC1 10V/m, 0.15-80MHz
Voltage dips & interruptions EN60947-4-2	IEC/ EN 61000-4-11 100% Ue dip, 20ms, PC2 60% Ue dip, 200ms, PC2 30% Ue dip, 500ms, PC3 100% Ue interruption, 5000ms, PC3 60% Ue dip, 100ms, PC2 60% Ue dip, 1000ms, PC2 30% Ue dip, 10ms, PC2 100% Ue interruption, 5000ms,PC3
Radio interference field emissions (radiated)	CISPR 11 IEC/ EN 55011, Class A
Radio interference voltage emissions (conducted)	CISPR 11 IEC/ EN 55011, Class A

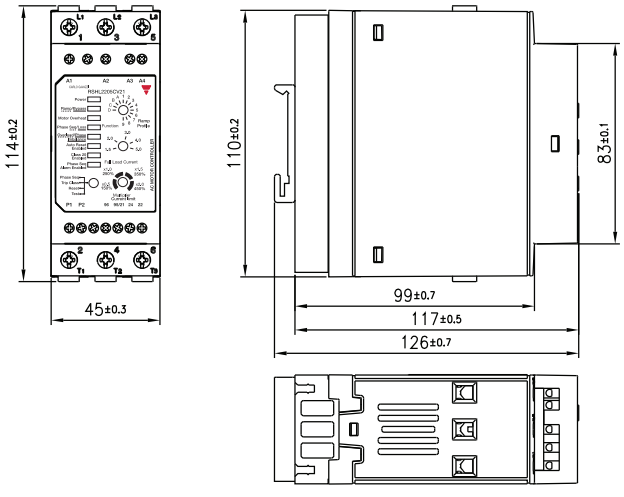
Note: EMC testing was performed with the RSHL connected to representative motor loads of 1.1/ 4.0kW. The EMC performance of the controller would eventually have to be evaluated with the controller connected and fitted as part of the complete system in the end application.

Terminal Diagram



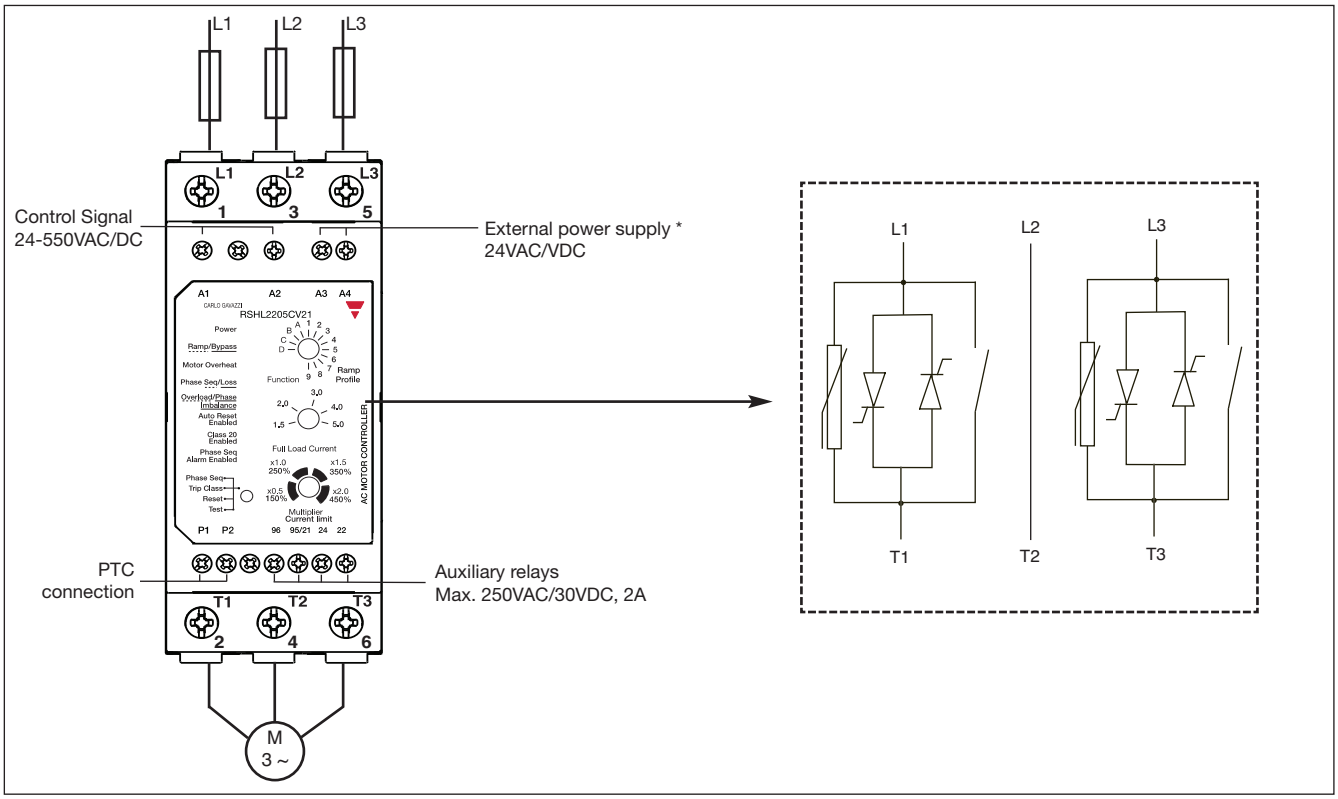
L1, L2, L3:	Mains supply
T1, T2, T3:	Motor supply
A1, A2:	Control input
A3, A4:	External supply
P1, P2:	PTC connection from motor
22:	End of Ramp (Normally Closed)
24:	End of ramp (Normally Open)
95/ 21:	Common
96:	Alarm (Normally closed)

Dimensions



All dimensions in mm

Connection Diagram



* For the 24VDC external supply, CG power supply model SPD24051 can be used

Short circuit Protection (according to EN/IEC 60947-4-2)

	RSHL..02CV21	RSHL..05CV21	RSHL..12CV21	RSHL..18CV21
Type of coordination: 2				
Rated short circuit current by semiconductor fuses	10kA when protected by semiconductor fuses	10kA when protected by semiconductor fuses	10kA when protected by semiconductor fuses	10kA when protected Semiconductor
fuse Ferraz Shawmut	Ferraz Shawmut 16A, Class URC Art. No. 6.9 CP gRC 14.51.16	Ferraz Shawmut 25A, Class URC Art. No. 6.9 CP gRC 14.51 25	Ferraz Shawmut 50A, Class A70QS Art. No. A70QS50-4	60A, Class A70QS Art. No. A70QS60-4

Electronic Overload Relay

Overload Trip Class in accordance to IEC 60947-4-1

Overload Condition	Class 10 (default)	Class 20 (user selected)
@ 1.05xIe (cold condition)	trip cannot be within 2 hrs	trip cannot be within 2 hrs
@ 1.2xIe (hot condition)	trip has to be within 2 hrs	trip has to be within 2 hrs
@ 1.5xIe (hot condition)	trip has to be within 240s	trip has to be within 480s
@ 7.2xIe (cold condition)	trip has to be within 4 to 10s	trip has to be within 6 to 20s

Note: Device remembers settings on loss of power but not overload condition.

Over-temperature Protection

Motor Overheat Protection

Motor PTC connection	P1:P2

PTC Resistance

< 500Ω	No Trip:	Normal Running
> 1000Ω	Trip:	Overheat Alarm LED & Alarm Relay Activated
< 300Ω	Reset	

Soft Starter Protection

Only available for RSHL..18CV21 units. In other models, the overload protection becomes active before the internal temperature protection

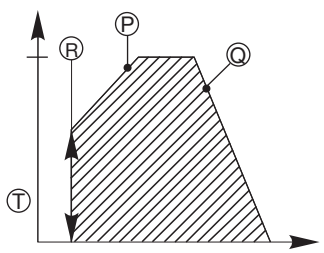
Alarms

Auxiliary Relays Connection 95/21: 96[1]	Alarm Output (Normally Closed).
Phase Sequence Alarm	Available when Phase Sequence Alarm is enabled. In such condition device is disabled and alarm indicated.[2]

Phase Loss Alarm Ramping Idling (when power supply is ON and Control Input is OFF)	Not present All three phases must be present for the device to operate. If any phase is missing, alarm is indicated.
Bypass Mode	Device will switch off motor, and alarm is indicated
Phase Imbalance Alarm Bypass Mode[3]	In Bypass mode, the device will trip if the amplitude of the current in one phase is greater than 50% of the one of the other two phases for 3 seconds.

Notes:
1 Activated in case of phase loss, phase sequence, phase imbalance, overheat and overload conditions, and shorted power devices. The respective LED indicates the type of alarm. During alarm conditions, if RSHL is in the running mode, it will cease to operate or if in the idling mode it will not start.
2 To operate the device in reversing mode the Phase Sequence Alarm should be disabled.
3 Manual resettable only.

Operational Diagram



Ⓟ Ramp-up time: time from zero load voltage to full load voltage.

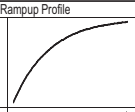
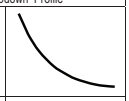
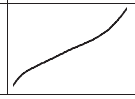
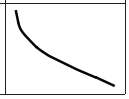
Ⓠ Ramp-down time: time from full load voltage to zero load voltage.

Ⓡ Initial voltage: voltage at the start of the ramp-up function..

Ⓣ Initial Torque

Operational Diagram

Ramp Profiles

Rampup Profile		Rampdown Profile	
Standard		Standard	
Linear Torque		2nd Polynomial	

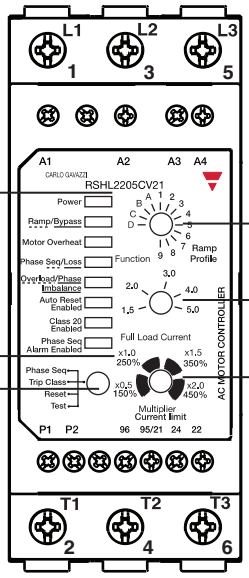
Parameter Settings

Selector (Knob 1)	Type of Load	Ramp-up			Ramp-down	
		Time (s)	Profile	Initial Voltage	Time (s)	Profile
1	General Purpose 1*	2	Standard Up	30%	0	No Ramp Down
2	General Purpose 2	10	Standard Up	30%	0	No Ramp Down
3	General Purpose 3	2	Standard Up	30%	10	Standard Down
4	General Purpose 4	10	Standard Up	30%	10	Standard Down
5	General Purpose 5	5	Standard Up	30%	0	No Ramp Down
6	General Purpose 6	5	Standard Up	40%	10	Standard Down
7	General Purpose 7	5	Standard Up	50%	10	Standard Down
8	Pump	5	Standard Up	30%	10	2nd Polynomial Down
9	Screw compressor	0.5	Linear Torque Up	20%	0	No Ramp Down
D	Current limit					
A	Auto/Man. Reset					
B	Trip Class 10/20					
C	Phase sequence alarm					

* Default

Push Button

Push (Button 4)
Default MANUAL (Hold Button: RESET) Default 10 (Hold Button: TEST) ENABLE or DISABLE: Default ENABLE



Current Settings

Part No.	Current Range (Knob 2)
RSHLxx**02**CV21	0.6 - 2A
RSHLxx**05**CV21	1.5 - 5A
RSHLxx **12**CV21	4.5 - 12A
RSHLxx **18**CV21	5 - 18A

Default: min. value

LED Nomenclature

xxxx	ON
xxxx	Flashing

Multiplier/ Current Limit

Multiplier/ Current Limit (Knob 3)
Ramp-up Time Multiplier by either 0.5, 1.0, 1.5, 2.0 (Default x1)
Either 150%, 250% 350%, 450%

LED indications

LED	STATUS		
	OFF	Flashing	ON
Green	Power OFF	N/A	Power ON
Yellow	Idle / Setup	Ramping*	Bypass ON
Red	N/A	Internal Overheat Alarm*	Motor Overheat Alarm
Red	N/A	Phase Sequence Alarm*	Phase Loss Alarm
Red	N/A	Overload Alarm*	Phase Imbalance Alarm
Yellow	Manual	N/A	Auto
Yellow	Class 10 Protection	N/A	Class 20 Protection
Yellow	Phase Sequence Alarm disabled	N/A	Phase Sequence Alarm Enabled

* Will flash simultaneously in case of fault

CARLO GAVAZZI

Mode of Operation

1. Connections

1.1 Power supply

In order to energize the RSHL an **external power supply** (24V AC/DC, 50/60Hz) should be connected between terminals **A3:A4**.

1.2 Control input

The **control input** is to be applied between connections **A1:A2**. The RSHL soft starter supports a control input signal rating of 24-550V AC/DC

1.3 Mains supply

The three wires of the **three-phase mains supply** is to be connected in terminals marked **L1**, **L2** and **L3** respectively.

1.4 Motor Connections: windings

The **three-phase motor** (load) is to be connected with terminals marked **T1**, **T2** and **T3**. The configuration of inside-delta is not supported in this device.

1.5 Motor Connections: PTC

If the motor is equipped with a **PTC** device (for the measurement of temperature) it can be connected between terminals **P1:P2**. PTC Characteristics should be as per DIN44081/2. If motor PTC is not connected, terminals P1 and P2 should be bridged with the link provided. Unconnected P1 and P2 terminals will trigger the motor over temperature alarm.

1.6 End of Ramp and Alarms

The device is equipped with two **auxiliary relay** outputs as follows:
(i) End of Ramp Normally Closed Terminals **21 : 22**, Normally Open Terminals **21 : 24**
(ii) Alarm Normally Closed Terminals **95 : 96**

2. Getting Started

Please refer to the "Operational Diagram"

2.1 Setting the Motor Full Load Current (Ie)

This is set to the desired level by adjusting the **Full Load Current Knob 2**. Caution should be taken to set the correct value as this might cause damage in either the device and/or the motor. Unless changing the motor this setting should never be changed.

2.2 Soft Start/Stop Settings

The user can chose either one of the **nine Standard ramping profiles** or a **Start with Current limit profile**. Please refer to the **"Operational Diagram"**

2.2.1 Selecting a Standard Ramping Profile

The selection of one of the nine Standard Ramping Profiles is made easy by turning the **Ramp Profile/Function (Selector Knob 1)** to the desired position according to the selection that is made after referring to **Parameter Setting Table** in the **"Operational Diagram"**.
Example: The desired profile is [ramp up=5s, ramp down=10s, initial torque=30%]. Select **Pump** by setting the **Selector Knob 1** to position **8**. Then proceed to set the Multiplier as explained in the next step.

2.2.2 Changing the Ramp-up Time of a Standard Ramping Profile

The **Multiplier/Current Limit Knob 3** allows an increase or reduction of the ramp-up time of the selected Standard Ramping Program.
Example: The **selector knob 1** has been set to position **8** and a ramp up time of **10s** is desired. The default ramp up of this program is **5s**. By setting the Multiplier to position **x2.0** the ramp up is time changed to **10s**.

2.2.3 Selecting and Setting the Current Limit profile

If **Current Limit profile** is desired instead of a **Standard Ramping Profile**, this is **selected by setting the Ramp Profile/Function Selector Knob 1** to position **D**. In Current Limit profile the device limits the inrush current during ramp-up to the current limit set by the user. The current limit level is set by turning the **Multiplier/Current Limit knob 3** to the desired percentage of Full Load Current (Ie).
Example: The Full Load Current (Ie) is 10A. The desired current limit is ≤40A. The Ramp Profile/Function selector knob 1 is turned to position **D**. The Multiplier knob 3 is turned to 350%. This will set the current limit to 35A which is within the desired range.

2.3 Overload Settings

The **overload functions** are set by using the **selector knob 1** in combination with the **push button 4**.

2.3.1 Selecting the Trip Class

This device can operate to either Trip Class 10 or Trip Class 20. The overload trip conditions are according to IEC 60947-4-1. These are summarised in the section entitled **Electronic Overload Relay**. Trip Class 10 is the default setting. To change to Trip Class 20, the Ramp Profile/Function **selector knob 1** is turned to position **B** and the **push button 4** is pressed once. The yellow LED marked **Class 20** goes ON. To change back to Trip Class 10, the **selector knob 1** is turned to position B and the **push button 4** is pressed once. The yellow LED marked Class 20 goes OFF.

2.3.2 Setting the Overload Reset Mode (Manual or Automatic)

Manual Reset is the default setting. To change to **Automatic Reset**, the **Selector Knob 1** is turned to position **A** and the push button 4 is pressed once. The yellow LED marked Auto Reset goes ON. To change back to Manual Reset, the **Selector Knob 1** is turned to position **A** and the **push button 4** is pressed once. The yellow LED marked Auto Reset goes OFF.

2.3.3 Overload Function Test

The **overload function test** works only when the device is idle. This function is not available if the device is either in the running (ramping or bypass) or in the alarm mode. To perform an overload function test, the **Selector Knob 1** is turned to position **B** and the **push button 4** is pressed and held down until the device enters the Overload Function Test (approximately 2 seconds). In this condition the red LED marked **Overload/Phase Imbalance** starts flashing. Further the load is disconnected and the Alarm Relay becomes active.
To exit the **overload function test** the user would need to turn **Selector Knob 1** to any Parameter Setting from 1 to 9 or to Position **D**, and **push button 4** is pressed and held down for approximately 2 seconds until the device exits the Overload Function Test.

2.4 Enabling and Disabling Phase Sequence Monitoring

Phase Sequence monitoring Enabled is the default setting. The yellow LED marked **Phase Seq Enable** is ON. To disable this function, the **Selector Knob 1** is turned to position **C** and the **push button 4** is pressed once. The yellow LED marked Phase Seq Enable goes OFF. To enable this function, the Selector Knob 1 is turned to position **C** and the **push button 4** is pressed once. The yellow LED marked Phase Seq Enable goes ON. When using a reversing relay in combination with this device, this function should be disabled.

3. LED Indication

Refer to the section entitled **LED indication**

4. Alarms

Refer to the section entitled **Alarms**. Reset of alarms are the same as for the overload as in 2.3.2.

5. Over-temperature Protection

Refer to the section entitled **Over-temperature Protection**.

6. Short-circuit Protection

Refer to the section entitled **Short-circuit Protection**, as in figure 1 of the wiring diagram.

7. Device Malfunction

In the case where the supply LED is ON and the four LED under it are flashing, this would indicate that the device is Faulty and should be returned for servicing.

Wiring Diagram

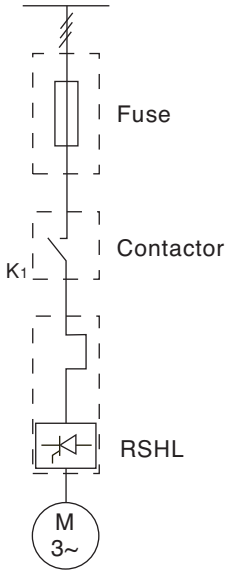


Fig. 1a

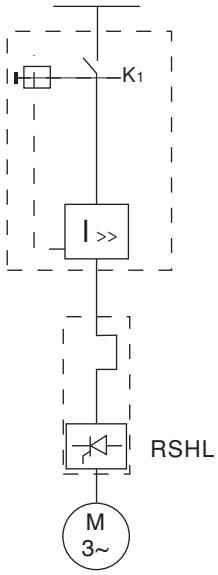


Fig. 2a

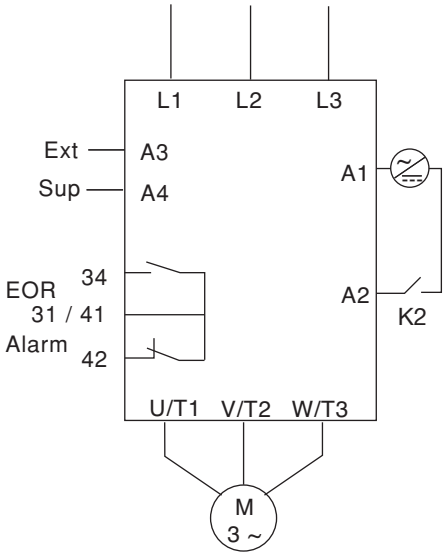


Fig. 3a

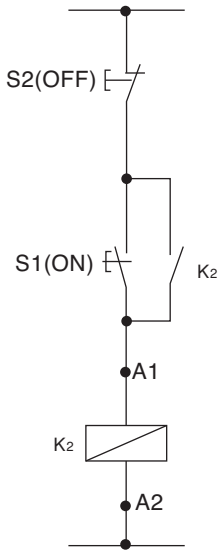


Fig. 4a

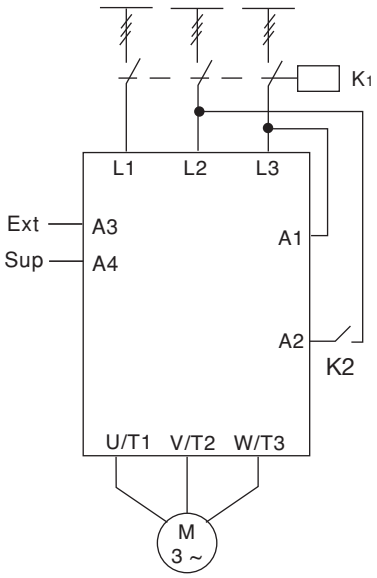


Fig. 5a

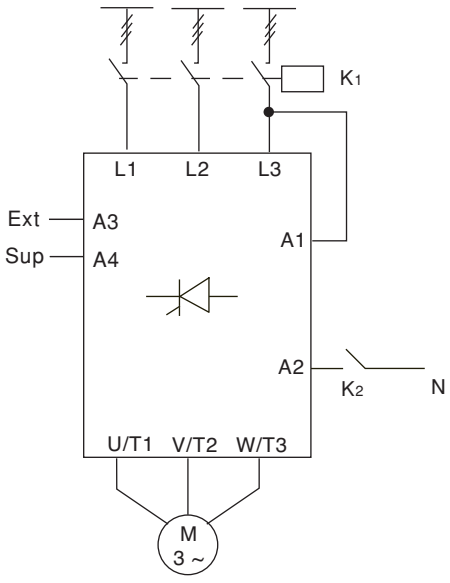


Fig. 6a

IEC

Wiring Diagram (cont.)

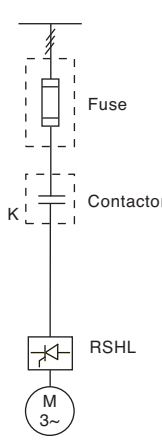


Fig. 1b

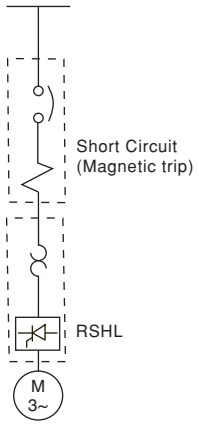


Fig. 2b

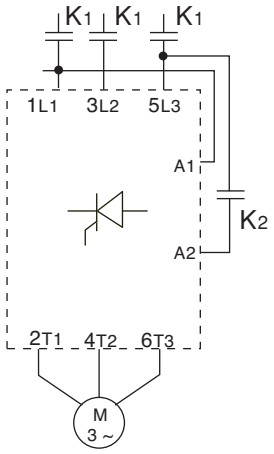


Fig. 5b

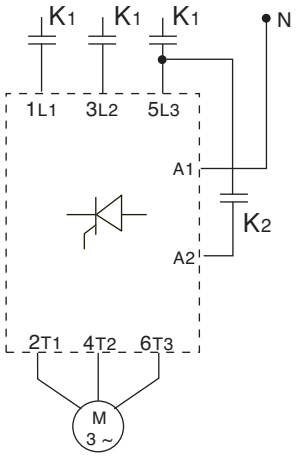


Fig. 6b

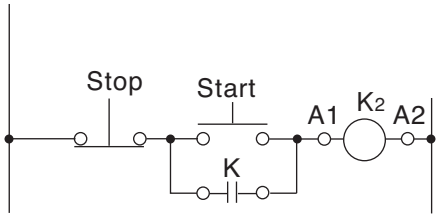


Fig. 4b

NEMA

On normal conditions the motor controller provides bypassing of the semiconductors during running operation. In case of Overload Conditions (current exceeds 20A) while in bypass mode, semi-conductors are again activated and bypass relays deactivated. Therefore the semiconductors can only be damaged by short-circuit currents during ramping (in normal conditions) or while in overload conditions. **Please note that the motor controller does not isolate the motor from the mains.**

Figure 1: Protection of the device when using fuses.
Protection with semiconductor fuses is intended to protect the motor feeder and motor controller from damage due to short-circuit. RSHL protects motor load in overload conditions.

Figure 2: Protection using a magnetic trip.
In this configuration, the motor and its feeder are protected for the overload condition by the internal overload protection of the RSHL. However, due to the relatively slow response of the magnetic trip and the in the absence of semiconductior fuses, damage to the motor controller can occur in this circuit topology.

Figure 3: Secondary conductors.
3.1: Control using a 2-position switch.
When K_2 is closed, the control input is supplied to A1 and A2 and soft starting of the motor is performed. When K_2 is opened, soft stopping is performed.

3.2: Auxiliary Relay
The End of Ramp (EOR) relay 34: 31/ 41 (Normally Open). If EOR is issued to activate external bypass contactors overload protection will be deactivated as current is shunted away from RSHL. Auxiliary alarm relay 31/ 41 : 42 is NC.
This relay is activated in case of any alarm.

Figure 4: Control using ON and OFF push buttons
Pushing S1 soft starts the RSHL. Pushing S2 soft stops the RSHL. K_2 is an auxiliary contact of the mains contactor.

Figure 5: Control using 2 phases
Connecting input A1, A2 to two of the incomming lines will soft start the motor when K_2 is operated. When K_2 is switched off, the motor will soft stop. This configuration does not apply to the RSHL60.CV21 versions.

Figure 6: Control when using operational voltage greater than 550V
Connecting A1 to Neutral and A2 to one of the incoming phases (or vice-versa) will soft start the motor when K_2 is closed. When K_2 is opened, the motor will soft stop.

Timing Diagram

Diagram 1: Normal Operation (Factory Defaults)

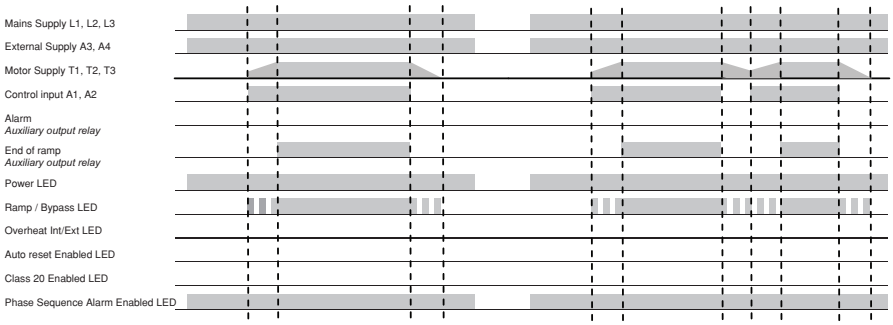


Diagram 2a: Over-temperature alarm during ramping mode

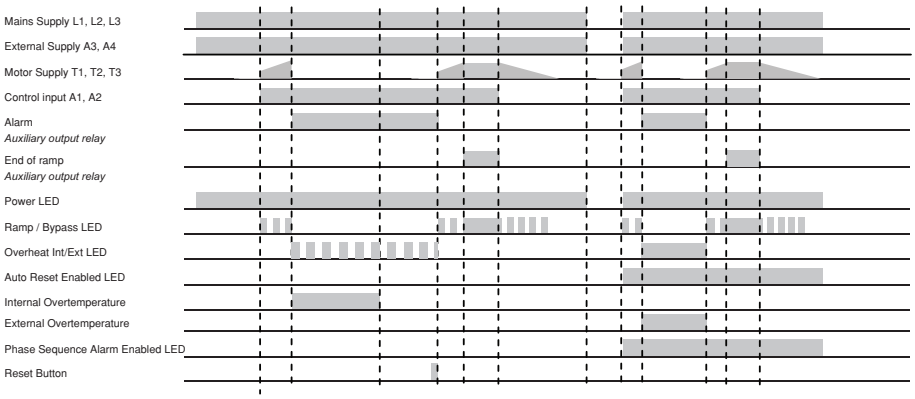
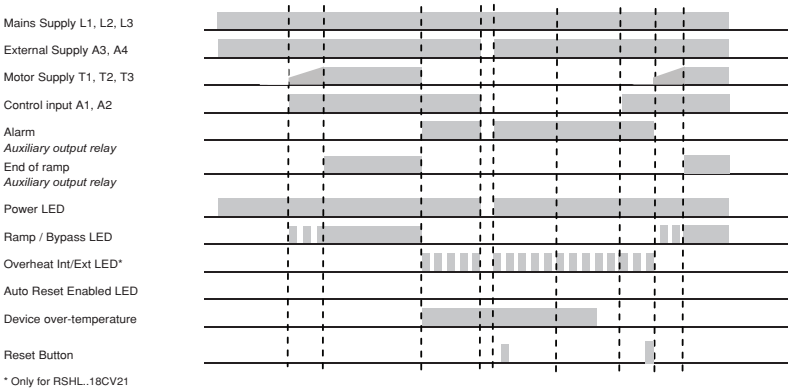
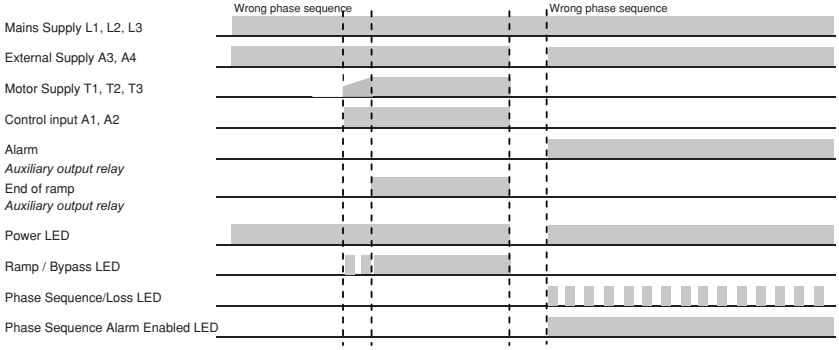


Diagram 2b: Over-temperature during bypass mode.



* Only for RSHL..18CV21

Diagram 2c: Wrong phase sequence alarm



Note:

1. If Phase Sequence Alarm is disabled (Phase Sequence Enabled LED is off); motor will rotate in the reverse direction, if any two phases are interchanged
2. Phase Sequence Alarm can either be reset manually or automatically

Timing Diagram (cont.)

Diagram 2d: Phase Loss during idling mode

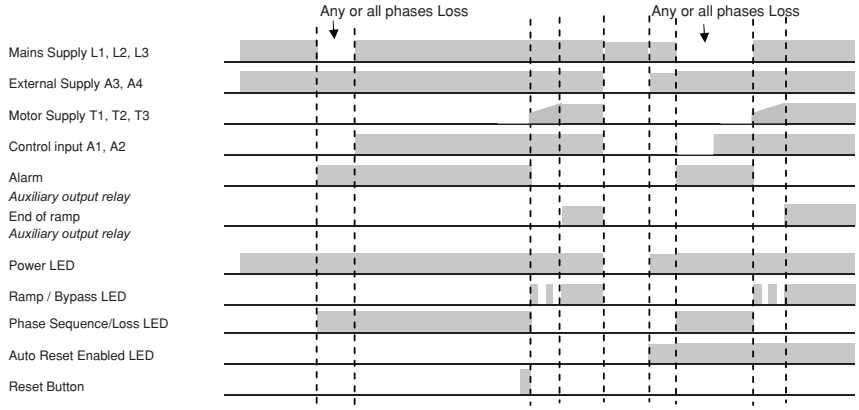


Diagram 2e: Phase Loss during bypass mode

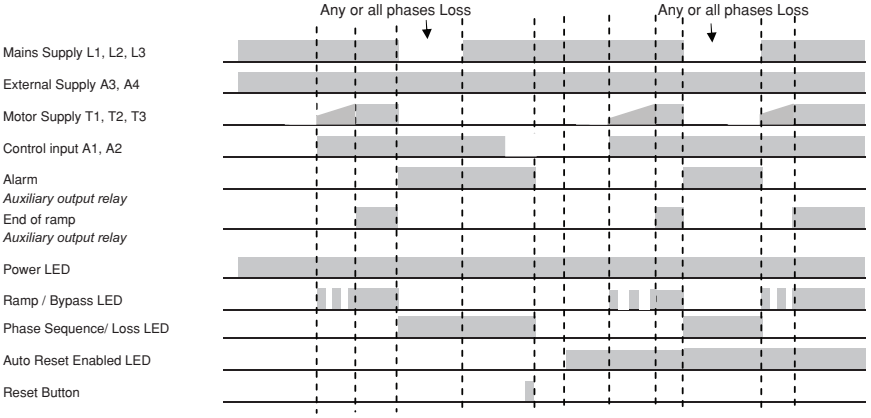
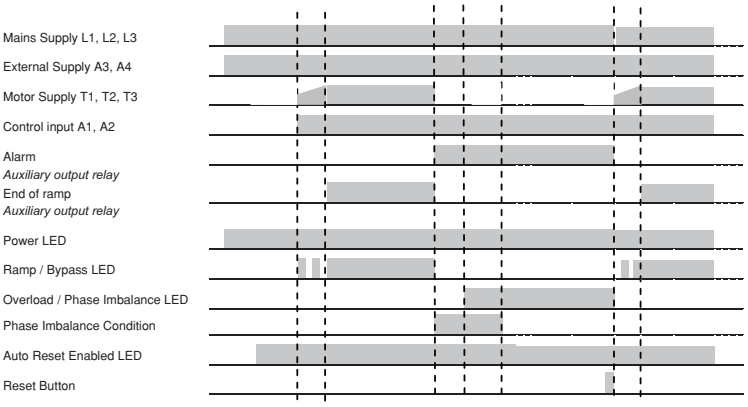


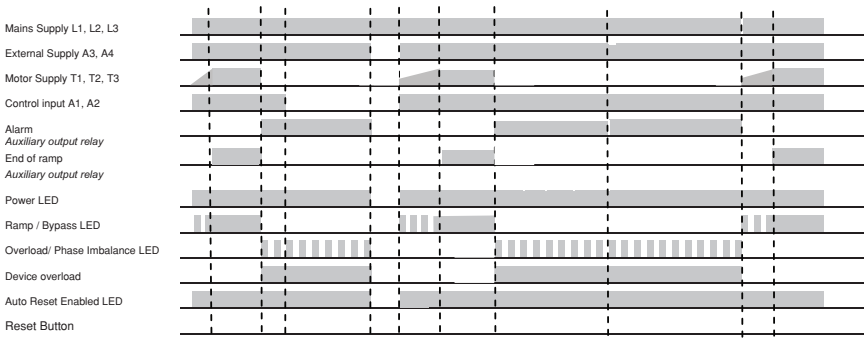
Diagram 2f: Phase Imbalance while in bypass mode



Note:
1. Phase Imbalance Alarm is indicated when the difference in current magnitude between respective phases is greater than 50% for more than 3s
2. Phase Imbalance Alarm can only be resetted manually.

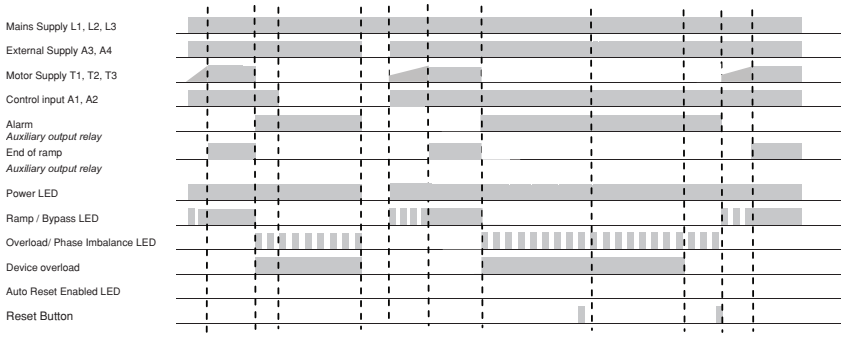
Timing Diagram (cont.)

Diagram 2g: Overload alarm (Automatic Reset)



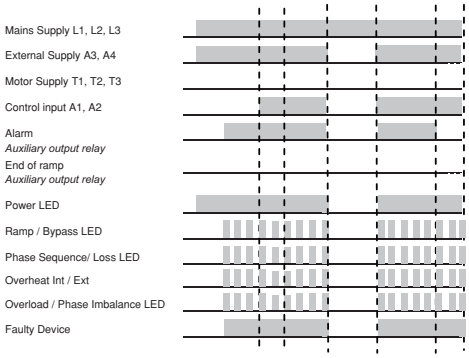
Note:
1. RSHL will only automatically reset Overload and resume normal running when sufficient cooling down time has passed.
2. In case of external supply cycling; user has to make sure that sufficient time for cooling is allowed.
   In case of insufficient cooling time motor and/or device may be damaged.

Diagram 2h: Overload alarm (Manual Reset)



Note:
1. After an current overload occures; a manual reset is only executed after sufficient time has passed for motor to cool down.
2. This precaution can be bypassed by power cycling.
3. In case of power cycling; user has to be sure that sufficient time for cooling is allowed.
   In case of insufficient cooling time motor and/or device may be damaged.

Diagram 2i: Faulty Device



Note:
1. This alarm can only be reset through External Power Supply Cycling. If Alarm does not reset with External Power Cycling, device is permanently damaged.

General Notes

Note 1: When a motor PTC is connected, electromagnetic noise may be conducted into the unit. Thus if abnormal function is obsereved, the use of ferrite beads on the PTC wire (at the end) is recommended.

Note 2: The overload alarm is determined by the Motor Current (Knob 2) setting and selection of the trip class. Please refer to operational diagram.

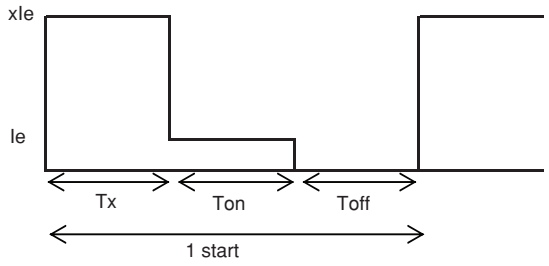
Note 3: Delay time between the moment of pressing the push button until the actual response is 2s.

Note 4: Since the RSHL Smart is a two-phase control the third-phase (L2 - T2) is always connected, and caution should be always observed.

Overload Cycle & Starting Duty

Overload profile

In: AC-53b: x-Tx: OFF time
where: Ie = nominal current through RSHL
x = overload current as a multiple of Ie
Tx = duration time for the controlled overload currents during starting
OFF time = minimum OFF time before a subsequent start may be initaiated



The following tables indicate the max. allowable no. of starts for Overload Profile:
Ie: AC-53b: 4-5: OFF time, Ton = 5sec

Example: To find the maximum no. of starts for RSHL4005CV21 at a nominal current of 10A at 50°C with 0mm spacing.
According to Table 1, the maximum no. of starts = 85, hence Overload Profile for this application would be:
10: AC-53b: 4-5: 32, i.e. an OFF time of 32s is required before any subsequent start may be initated

Spacing: 0mm

Table 1: RSHRxxyyCV21, where xx = 22 or 48, yy = 02 or 05

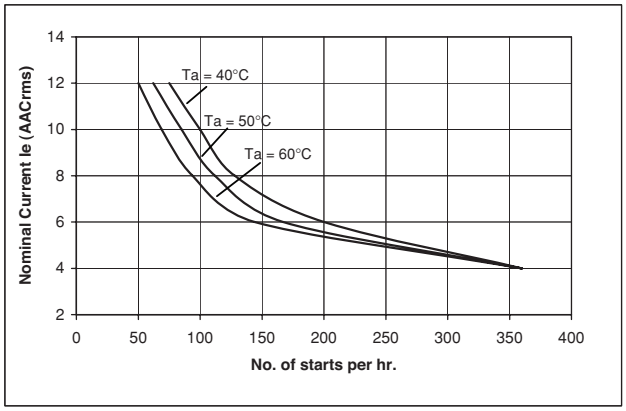


Table 2: RSHRxxyyCV21, where xx = 22 or 48, yy = 12 or 18

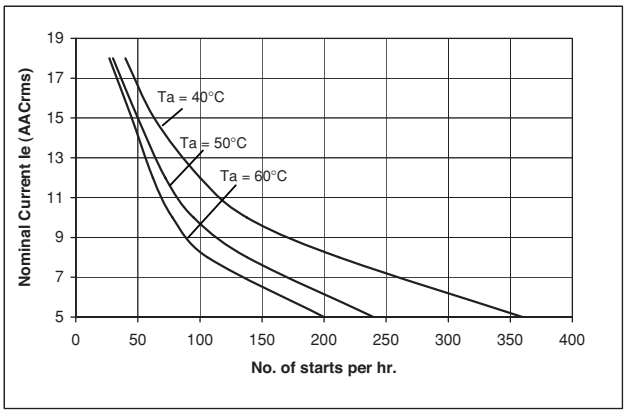
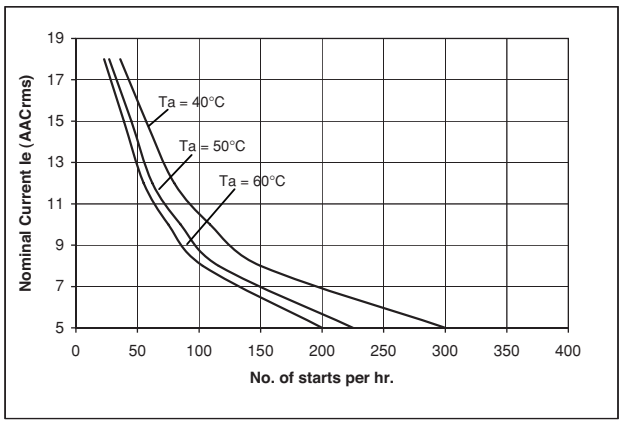


Table 3: RSHR60yyCV21, where yy = 02, 05, 12 or 18



Overload Cycle & Starting Duty (cont.)

Spacing: 45mm

Table 4: RSHRxxyyCV21, where xx = 22 or 48, yy = 02 or 05

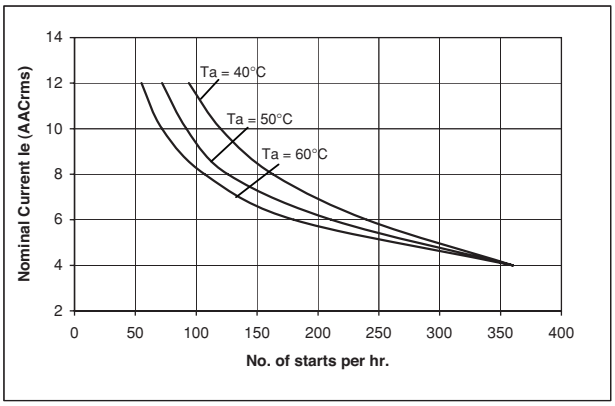


Table 5: RSHRxxyyCV21, where xx = 22 or 48, yy = 12 or 18

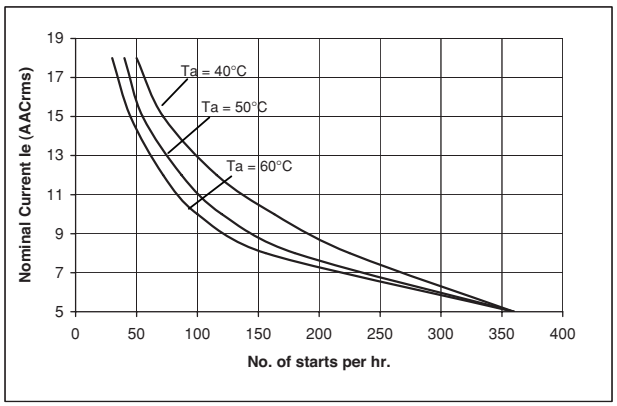
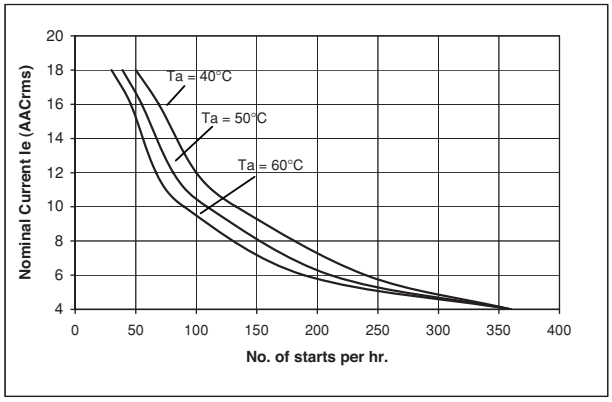


Table 6: RSHR60yyCV21, where yy = 02, 05, 12 or 18



Accessories - External Power Supply 24VDC - SPD 24051

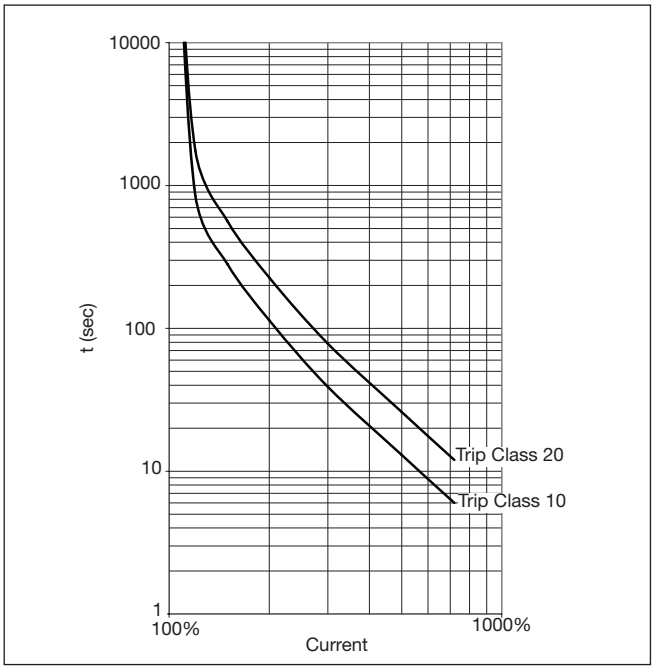
Rated input voltage		100-240
Voltage range	AC	90 - 265VAC
	DC	120 - 370VDC
Frequency range		47 - 63Hz

Voltage trim range	21.6 - 28.8VDC
Output voltage accuracy	± 1%
Output current	0.21A

For further details refer to Carlo Gavazzi SPD series datasheet

Overload Characteristics

Cold Trip



Hot Trip